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# LERNER AND GREENBERG, P.A.

PATENT ATTORNEYS AND ATTORNEYS AT LAW

2445 Hollywood Boulevard  
Hollywood, Florida 33020  
Tel: (954) 925-1100  
Fax: (954) 925-1101

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11/20/00

Herbert L. Lerner (NY Bar)  
Laurence A. Greenberg (FL Bar)

Werner H. Stern (FL Bar), Senior Attorney

Ralph E. Locher (FL, IL, MO Bars)  
Manfred Beck (US & German Pat. Agent)  
Mark P. Weichselbaum (TN Bar)  
Gregory L. Mayback (FL Bar)  
Markus Nolff (FL Bar)  
Otto S. Kauder (Reg. Pat. Agent)  
Loren Donald Pearson (FL Bar)

PATENTUSA<sup>SM</sup>  
www.patentusa.com  
patents@patentusa.com

New York Office  
153 E 57th Street  
Suite 15G  
New York, NY 10022

Mailing Address:  
Post Office Box 2480  
Hollywood, FL 33022-2480

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Docket No.: INF-P10182

  
MICHAEL BURNS

Date: November 20, 2000

Hon. Commissioner of Patents and Trademarks  
Washington, D.C. 20231

Sir:

Enclosed herewith are the necessary papers for filing the following application for Letters Patent:

Applicant : DIETER DRAXELMAYR

Title : METHOD OF COMMUNICATING WITH A BUILT-IN SENSOR, IN PARTICULAR A ROTATIONAL SPEED SENSOR

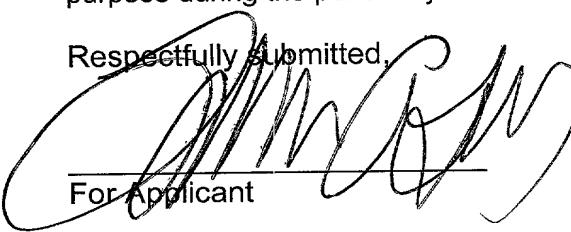
3 sheets of formal drawings in triplicate.

A check in the amount of \$710.00 covering the filing fee.

This application is being filed without a signed oath or declaration under the provisions of 37 CFR 1.53(d). Applicants await notification of the date by which the oath or declaration and the surcharge are due, pursuant to this rule.

The Patent and Trademark Office is hereby given authority to charge Deposit Account No. 12-1099 of Lerner and Greenberg, P.A. for any fees due or deficiencies of payments made for any purpose during the pendency of the above-identified application.

Respectfully submitted,

  
For Applicant

LAURENCE A. GREENBERG  
REG. NO. 29,302

LAG:tk

METHOD OF COMMUNICATING WITH A BUILT-IN SENSOR,

IN PARTICULAR A ROTATIONAL SPEED SENSOR

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Background of the Invention:

Field of the Invention:

The present invention relates to a method of communicating with a built-in sensor, in particular a rotational speed

10 sensor, which supplies an output signal with successive signal pulses. In a preferred embodiment, the sensor is built into a motor vehicle in such a way that it can be supplied with a supply voltage externally via a voltage supply line.

15 Although applicable to any desired sensors, the present invention and the problem area on which it is based are explained using a rotational speed sensor which supplies successive logic L and H signal pulses as output signal.

20 The prior art discloses various rotational speed sensors which are intended to be able to detect the revolutions of a wheel. By way of example, a sensor with a gearwheel is known, in which the teeth and gaps of the gearwheel are converted into logic H=HIGH and L=LOW states, respectively. In the case of a 25 prior art two-wire current interface, these states are output such that each state is assigned a specific current

consumption. As a result, the two supply lines can simultaneously be used as signal output lines as well.

A rotational speed sensor with a three-wire voltage interface 5 is likewise known. In that case, too, the three supply lines can simultaneously be used as signal output lines as well.

In the prior art sensors of that type, however, it is not readily possible to ascertain the operational reliability with 10 which it is operating. Depending on where it is built in, it may receive a very large or a very small input signal.

Monitoring the mechanical assembly would be better served by an additional signal allowing a statement about the magnitude of the sensor signal.

15 More generally, the sensor is, as a rule, built into the motor vehicle at an inaccessible location, so that direct communication with the associated integrated intelligent circuit is not possible. Only the supply lines of the 20 rotational speed sensor are freely accessible after the latter has been built in.

Therefore, in the case of the known approach above, what has turned out to be disadvantageous is the fact that it is no 25 longer possible to perform programming or interrogation for a read-out of the sensor in the built-in state.

It was proposed, therefore, that the sensor send digital output data in a specific protocol which, in a specific reserve bit, can signal that a specific input signal magnitude 5 has been exceeded. In general, it would be desirable at the same time to output the complete information about the input signal in this way, but the protocol is relatively simple and slow for reasons of interference immunity.

10 Summary of the Invention:

The object of the invention is to provide a method of communicating with a built-in sensor which overcomes the above-noted deficiencies and disadvantages of the prior art devices and methods of this kind, and in which it is possible 15 to perform programming or interrogation for a read-out of the sensor in the built-in state without the operational reliability being reduced.

With the above and other objects in view there is provided, in 20 accordance with the invention, a method of communicating with a built-in sensor, such as a rotational speed sensor which, in a preferred embodiment may be built into a motor vehicle, the sensor receiving a supply voltage externally via a voltage supply line and outputting an output signal with successive 25 signal pulses. The novel method comprises the steps of:

placing the sensor into a detection mode;

externally modulating the supply voltage on the voltage supply line connected to the sensor;

analyzing the modulated supply voltage received in the sensor

5 with regard to a fulfillment of a predetermined criterion stored in the sensor; and

interpreting the received modulated supply voltage as an external communication signal if the criterion is fulfilled.

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10 In other words, the concept underlying the present invention is found in the method steps which are carried out after the rotational speed sensor has been put into a detection mode: providing an external modulation of the supply voltage on the voltage supply line; analyzing the modulated supply voltage received in the sensor with regard to the fulfillment of a predetermined criterion stored in the sensor; and interpreting the received modulated supply voltage as an external communication signal if the criterion is fulfilled.

15

20 The novel method provides the particular advantage over the prior art solution approaches that it is possible to perform programming or interrogation for a read-out of the sensor in the built-in state without the operational reliability being reduced. In particular, it is possible to signal to the sensor

the desire for a test mode which is largely insusceptible to interference.

In accordance with an added feature of the invention, the  
5 sensor outputs as its output signal a signal with successive  
logic L and H signal pulses.

In accordance with an additional feature of the invention, the  
sensor is a rotational speed sensor supplied externally via a  
10 two-wire current interface, and the method further comprises:

comparing the modulated supply voltage received in the  
rotational speed sensor with an associated sensor current; and  
interpreting the received modulated supply voltage as an  
external communication signal if a negative resistance  
15 characteristic is ascertained.

In accordance with another feature of the invention, the  
rotational speed sensor is switched into a communication mode  
if a negative resistance characteristic is ascertained over a  
20 predetermined number of cycles of the sensor output signal of  
respective L and H signal pulses.

In accordance with a further feature of the invention, in the  
communication mode, each modulation of the supply voltage

having a predetermined signal duration and signal magnitude is interpreted as an external communication signal.

In accordance with again an added feature of the invention, a 5 logic "1" corresponds to an H pulse with 2/3 period duration and an L pulse with 1/3 period duration.

Furthermore, a logic "0" may be defined as corresponding to an H pulse with 1/3 period duration and an L pulse with 2/3 10 period duration.

In accordance with again an additional feature of the invention, in the communication mode, outputting with the rotational speed sensor communication signals on the voltage 15 supply line to an externally accessible terminal.

In accordance with again another feature of the invention, the supply voltage is maintained substantially constant in a case 20 of no communication.

In accordance with again a further feature of the invention, the rotational speed sensor is connected to and can be supplied externally via a three-wire voltage interface.

25 In accordance with yet an added feature of the invention, in the communication mode, the rotational speed sensor outputs

communication signals on the voltage output line to an externally accessible terminal point.

Other features which are considered as characteristic for the 5 invention are set forth in the appended claims.

Although the invention is illustrated and described herein as embodied in a method of communicating with a built-in sensor, in particular a rotational speed sensor, it is nevertheless

10 not intended to be limited to the details shown, since various modifications and structural changes may be made therein without departing from the spirit of the invention and within the scope and range of equivalents of the claims.

15 The construction and method of operation of the invention, however, together with additional objects and advantages thereof will be best understood from the following description of specific embodiments when read in connection with the accompanying drawings.

20

Brief Description of the Drawings:

Fig. 1 is a schematic block diagram of a prior art rotational speed sensor circuit with a two-wire current interface;

Fig. 2 is a schematic block diagram of a further prior art rotational speed sensor circuit with a three-wire voltage interface;

5 Figs. 3A and 3B are signal diagrams illustrating, with respect to time, signal magnitudes of the circuit according to Fig. 1, wherein Fig. 3A represents the known measurement mode and Fig.

3B illustrates the changeover to the communication mode; and

10 Figs. 4A, 4B, and 4C are signal diagrams illustrating the transmitted signal pulses in an embodiment of the method according to the invention.

Identical and functionally equivalent component parts are  
15 identified with the same reference symbols throughout the figures.

Description of the Preferred Embodiments:

Referring now to the figures of the drawing in detail and  
20 first, particularly, to Fig. 1 thereof, there is seen a schematic illustration of a prior art rotational speed sensor circuit with a two-wire current interface.

In Fig. 1, the reference symbol Vbat designates a battery  
25 voltage, 10 designates a voltage modulation/demodulation circuit, Vi designates a supply voltage, L designates a

voltage supply line,  $R_S$  designates a detection resistor,  $V_R$  designates a detection voltage,  $S$  designates a sensor with an intelligent circuit,  $I_S$ ,  $V_S$  designate the sensor current and the sensor voltage, respectively, and GND designates ground.

5

Fig. 2 shows a schematic illustration of a further prior art rotational speed sensor circuit with a three-wire voltage interface.

10 In the Fig. 2 circuit, a detection resistor  $R_S$  is not provided, rather a voltage detection line  $L_S$  is additionally routed to the "outside".

15 In both circuits, the sensor  $S$  with the intelligent circuit is no longer accessible after being built into the motor vehicle, but rather is "reachable" from outside only via the supply line  $L$  or voltage output line or ground line.

20 An exemplary embodiment of the invention is explained in more detail below with reference to the circuit according to Fig. 1.

1.

25 Figs. 3A and 3B show an illustration with respect to time of signal magnitudes in the circuit according to Fig. 1. More specifically, Fig. 3A illustrates the prior art measurement

mode and Fig. 3B illustrates the changeover to the communication mode.

In this exemplary embodiment, it is proposed, for the 5 changeover to the communication mode, to choose a voltage supply which has a negative resistance characteristic.

Operation is then as follows:

If the sensor S recognizes a rotating wheel, then it modulates

10 its current consumption accordingly and supplies successive logic L and H signal pulses as output signal. That detection state is illustrated in Fig. 3A. The supply voltage  $V_i$  is essentially constant, i.e. apart from operationally dictated fluctuations which, however, are not intended to have any 15 consequences with regard to the chosen mode. The sensor current  $I_s$  has a square-wave form and varies between 7 mA and 14 mA and the sensor voltage  $V_s$  correspondingly varies between 8 V and 10 V.

20 The voltage supply provides the sensor S with a low voltage in the case of a high current consumption and with a high voltage in the case of a low current consumption. Both supply voltages may perfectly well lie within the normal operating range.

25 In order to signal a desired communication or a communication mode, the voltage modulation/demodulation circuit 10 modulates

the supply voltage  $V_i$ , as illustrated in Fig. 3B. In this case, the voltage supply supplies the sensor S with a high voltage in the case of a high current consumption and with a low voltage in the case of a low current consumption. In other words, a negative resistance characteristic is prescribed, or a phase shift by  $0^\circ$  between sensor current  $I_s$  and sensor voltage  $V_s$ .

If the intelligent circuit of the sensor S then recognizes this state without interruption for a certain number of pulses (or a certain time), then the sensor switches into the test mode or communication mode. Since a negative resistance does not normally occur in real systems, "inadvertent" activation of the communication mode is largely prevented.

This principle can be refined further. By prescribing specific voltage levels which must be present in the case of a specific current consumption, it is possible for the interference immunity also to be increased.

It is also conceivable to provide a plurality of possible "low" and "high" supply voltages which must be activated in a specific order to activate a specific communication mode. As a result, it would even be possible to effect selection between different communication modes.

It is not important here to provide a concrete numerical value for the negative resistance of the voltage supply. On the contrary, it may even be useful if this relationship exists only in discrete form (a specific current consumption range is 5 assigned a specific voltage value) in order to reduce the risk of oscillation that otherwise arises.

If the communication mode has been attained, then the sensor behavior has to be changed over. In this case, it is possible 10 to convert internal analog signals, for example the (amplified) sensor input signal, into a current and to output the same in analog form. Furthermore, it is also possible, of course, to switch the data protocol into a specific communication mode and thus be able to transmit significantly 15 more data than normal.

The following procedure may be employed: During normal operation, the sensor S operates, as already described, with a slow, interference-immune protocol; consisting of logic "0" 20 and "1" information items reflected in the current consumption of the sensor in accordance with Fig. 3A. In this case, the sensor operates in a wide operating voltage range (for example 4.5 - 24 V). If the operating voltage exceeds 9.5 V in the course of the high current consumption and falls below 8.5 V 25 in the course of the negative current consumption (i.e. negative resistance) and this state lasts continuously over a

specific number of data changes, then the sensor switches into the communication mode. The time immediately after the changeover of the current level is masked out here in order to give the supply voltage source time to establish the new 5 voltage level. When the circuit is in the communication mode, a changeover is made to another data protocol.

In order to return to the case of normal operation, the following options are available: software reset by data 10 protocol, switch off and switch on operating voltage, or a supply voltage greater than 5V for a certain duration (longer than 150  $\mu$ s). The latter condition has the aim of automatically switching the chip back to normal operation under normal operating conditions (where the supply voltage is 15 greater than 5 V). Specifically, the data protocol in the test mode is configured in such a way that operating voltages of less than 5 V are normally used.

The communication interface protocol then functions as follows 20 in the case of this example: the default position of the supply voltage is low (< 5 V). If a data word is desired to be transmitted, then a series of pulses are sent. A logic 1 is represented therein by a High pulse with 2/3 period duration and a Low pulse with 1/3 period duration; a logic 0 is 25 represented by a High pulse with 1/3 period duration and a Low

pulse with 2/3 period duration. At the end, a stop bit is also sent, which signals the end of the transmission. In this case, the duration of the High pulse is noncritical (1/3 or 2/3 period); all that is important is that the succeeding Low

5 pulse is long enough ( $> 1$  period). That is the signal that a complete word has now been transmitted. A new pulse train, representing the next word, can then be transmitted anytime afterwards.

10 Referring now to Figs. 4A, 4B, and 4C, there are illustrated the transmitted signal pulses as a function of the time  $t$  in one embodiment of the method according to the invention.

In the simulation of a pulse train in Fig. 4:

15 • a switch is made from normal operation to the communication mode;

• data are transmitted; and

• a return is made to normal operation.

20 The signal  $V_i$  symbolizes the value of the supply voltage of the intelligent circuit of the sensor S ("0" signifies below 5 V, and high signifies above 5 V or, in order to attain the communication mode, even above 7 V). The signal  $I_s$  represents

the current consumption of the sensor S (high or low current consumption, as illustrated in Fig. 3).

First of all, as illustrated in Fig. 4A, the circuit is in the 5 normal mode. The circuit outputs a high or low current consumption  $I_S$  during normal operation. As a reaction to this, the supply voltage  $V_i$  is set to a high or low value. A changeover is then made to the communication mode with the 6<sup>th</sup> edge of  $I_S$ . Three (3) data words DW1 to DW3 are then 10 transmitted. Finally, the supply voltage  $V_i$  is increased for a relatively long time. This leads to a return to the normal mode.

Fig. 4B shows, as a detail, the transmission of the second 15 data word DW2. The word comprises 13 data bits and a stop bit. It can be seen that a new bit comes with each rising edge of  $V_i$ . Furthermore, it can be seen that logic ones and zeros are transmitted.

20 Fig. 4C shows, again in a detail enlargement, the transmission of one bit: as a reaction to a rising edge in  $V_i$ , a shift clock signal is generated (bit boundary). From the outside, that can be recognized from the fact that a new output bit appears with a certain delay.

This technique makes it possible, then, to obtain unlimited access to the communication interface of the sensor module. In the specific case, it is thus possible to access registers containing the present magnitude of the magnet signal.

5

Furthermore, the circuit also contains registers which store minimum and maximum magnet values. Moreover, there are status information items. As a result, it is now possible to read out the magnet signal digitally and to use the sensor in a way as

10 measuring means.

It will be understood by those of skill in the pertinent art that, although the present invention has been described above using a preferred exemplary embodiment, it is not restricted thereto but rather can be modified in diverse ways.

The sensor does not have to be built into a motor vehicle, but can also be built into a household appliance, for instance, such as a washing machine.

20

In particular, although the above embodiment relates to a two-wire current interface, the invention can, of course, also be applied to a three-wire voltage interface or other interfaces.

25 Moreover, it is possible to provide any desired external modulations of the supply voltage on the voltage supply line,

which are analyzed in the rotational speed sensor with regard to the fulfillment of a predetermined criterion stored in the rotational speed sensor, in order to be interpreted as an external communication signal if the criterion is fulfilled.

5

Moreover, the invention is not restricted to a rotational speed sensor, but rather can be applied to any desired sensors, such as e.g. pressure sensors, acceleration sensors, and the like. Likewise, logic output signals do not have to be 10 present during sensor operation, rather there may be any desired signal pulses.

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I claim:

1. A method of communicating with a built-in sensor, the sensor receiving a supply voltage externally via a voltage supply line and outputting an output signal with successive signal pulses, the method which comprises the steps of:

placing a sensor into a detection mode;

externally modulating a supply voltage on a voltage supply line connected to the sensor;

analyzing the modulated supply voltage received in the sensor with regard to a fulfillment of a predetermined criterion stored in the sensor; and

interpreting the received modulated supply voltage as an external communication signal if the criterion is fulfilled.

2. The method according to claim 1, which comprises outputting with the sensor an output signal having successive logic L and H signal pulses.

3. The method according to claim 1, wherein the sensor is a rotational speed sensor and the method further comprises:

supplying the rotational speed sensor externally via a two-wire current interface;

comparing the modulated supply voltage received in the rotational speed sensor with an associated sensor current; and

interpreting the received modulated supply voltage as an external communication signal if a negative resistance characteristic is ascertained.

4. The method according to claim 3, which comprises switching the rotational speed sensor into a communication mode if a negative resistance characteristic is ascertained over a predetermined number of cycles of the sensor output signal of respective L and H signal pulses.

5. The method according to claim 4, which comprises, in the communication mode, interpreting each modulation of the supply voltage having a predetermined signal duration and signal magnitude as an external communication signal.

6. The method according to claim 5, wherein a logic "1" corresponds to an H pulse with 2/3 period duration and an L pulse with 1/3 period duration.

7. The method according to claim 5, wherein a logic "0" corresponds to an H pulse with 1/3 period duration and an L pulse with 2/3 period duration.

8. The method according to claim 4, which comprises, in the communication mode, outputting with the rotational speed sensor communication signals on the voltage supply line to an externally accessible terminal.

9. The method according to claim 1, which comprises maintaining the supply voltage substantially constant in a case of no communication.

10. The method according to claim 4, wherein the rotational speed sensor is connected to and can be supplied externally via a three-wire voltage interface.

11. The method according to claim 10, wherein, in the communication mode, outputting with the rotational speed sensor communication signals on the voltage output line to an externally accessible terminal point.

12. The method according to claim 1, wherein the sensor is a rotational speed sensor.

13. The method according to claim 1, wherein the sensor is a rotational speed sensor built into a motor vehicle and the method comprises measuring a rotary speed of a motor vehicle component.

14. The method according to claim 1, wherein the sensor is built into a motor vehicle and is externally accessible via the voltage supply line.

15. The method according to claim 1, wherein the sensor is built into a household appliance and is externally accessible via the voltage supply line.

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Abstract of the Disclosure:

The method allows communication with a built-in sensor, in particular a rotational speed sensor, which supplies successive signal pulses as output signal. The sensor is

5 preferably built into a motor vehicle in such a way that it can be supplied with a supply voltage externally via a voltage supply line. The sensor is placed into a detection mode. The supply voltage on the voltage supply line is externally modulated. The modulated supply voltage received in the sensor

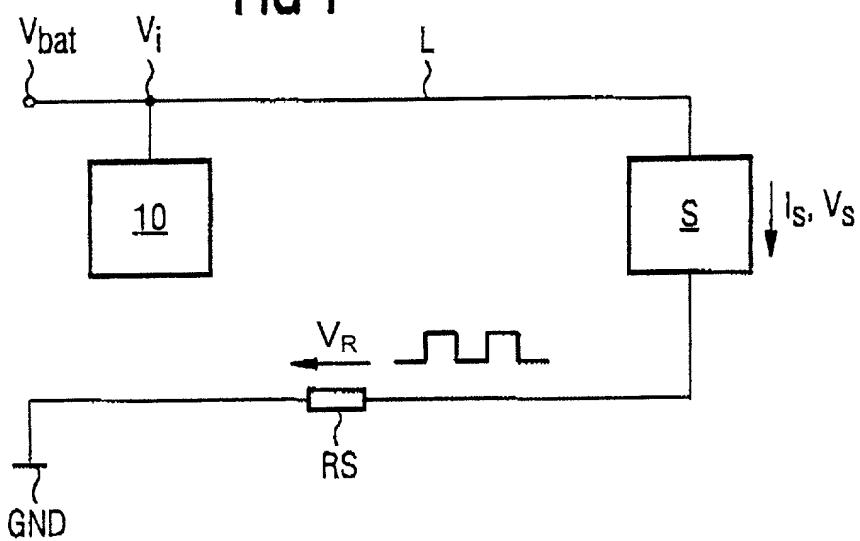
10 is analyzed with regard to the fulfillment of a predetermined criterion stored in the rotational speed sensor. And, finally, the received modulated supply voltage is interpreted as an external communication signal if the criterion is fulfilled.

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PRIOR ART

FIG 1



PRIOR ART

FIG 2

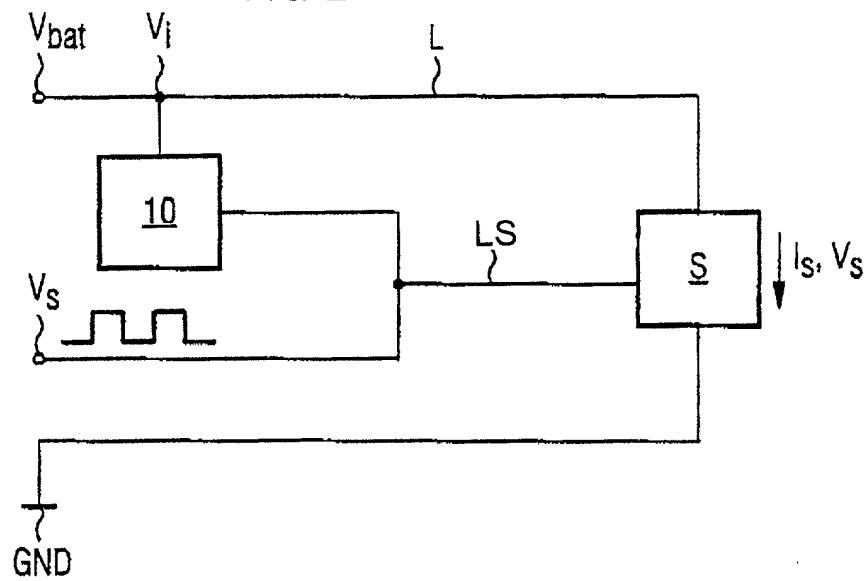


FIG 3A

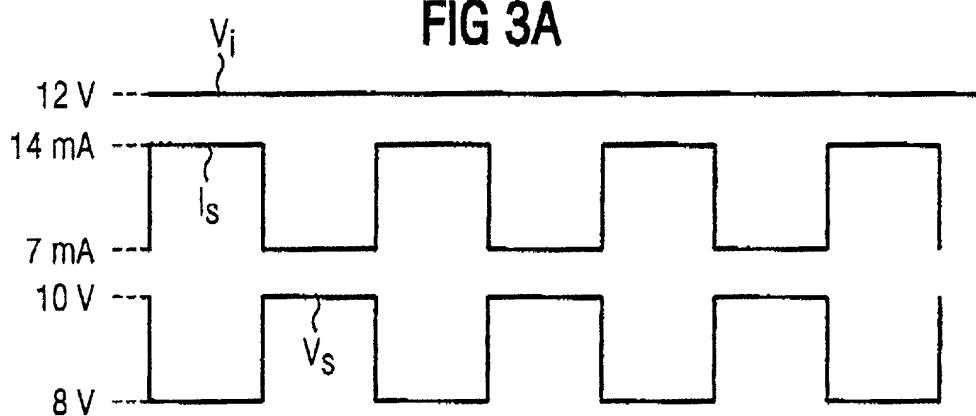


FIG 3B

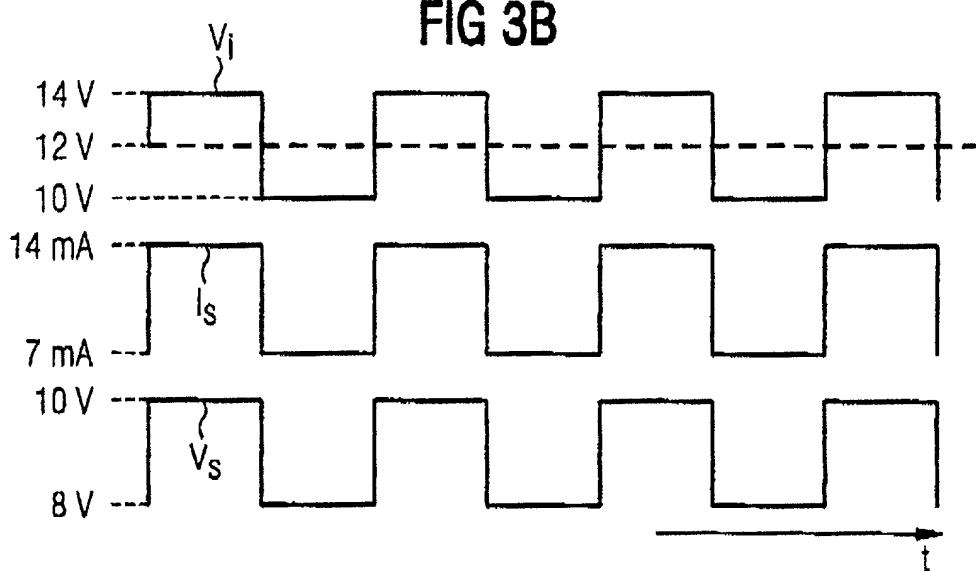


FIG 4A

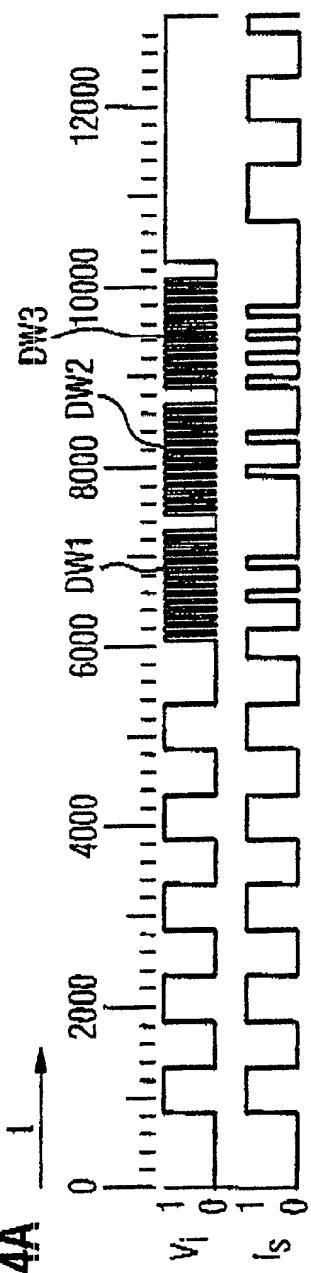


FIG 4B

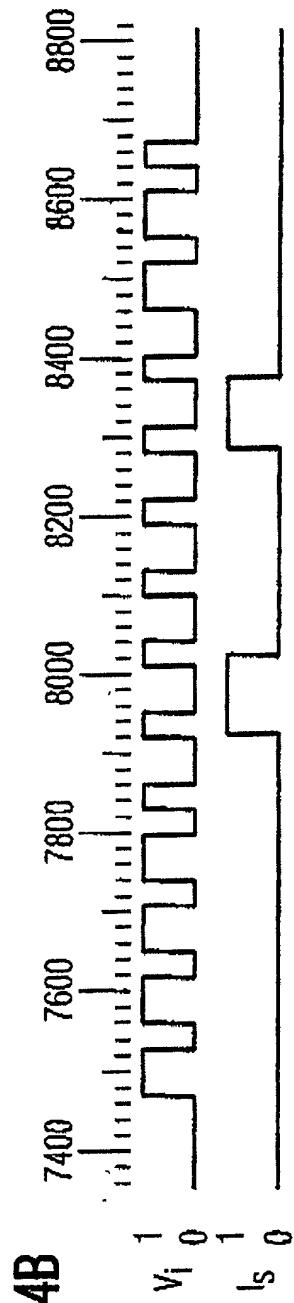
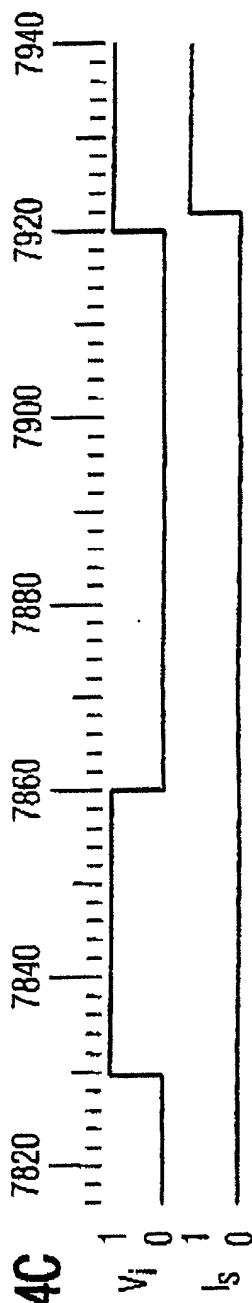


FIG 4C



**COMBINED DECLARATION AND POWER OF ATTORNEY  
IN ORIGINAL APPLICATION**

As a below named inventor, I hereby declare that: my residence, post office address and citizenship are as stated below next to my name; that I verily believe that I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled:

**METHOD OF COMMUNICATING WITH A BUILT-IN SENSOR,  
IN PARTICULAR A ROTATIONAL SPEED SENSOR**

described and claimed in the specification bearing that title, that I understand the content of the specification, that I do not know and do not believe the same was ever known or used in the United States of America before my or our invention thereof, or patented or described in any printed publication in any country before my or our invention thereof or more than one year prior to this application, that the same was not in public use or on sale in the United States of America more than one year prior to this application, that the invention has not been patented or made the subject of an inventor's certificate issued before the date of this application in any country foreign to the United States of America on an application filed by me or my legal representatives or assigns more than twelve month prior to this application, that I acknowledge my duty to disclose information of which I am aware which is material to the examination of this application under 37 C.F.R. 1.56a, and that no application for patent or inventor's certificate of this invention has been filed earlier than the following in any country foreign to the United States prior to this application by me or my legal representatives or assigns:

German Application No. 199 55 758.6, filed November 19, 1999, the International Priority of which is claimed under 35 U.S.C. §119.

I hereby appoint the following attorney(s) and/or agent(s) to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith:

HERBERT L. LERNER (Reg.No.20,435)  
LAURENCE A. GREENBERG (Reg.No.29,308)  
WERNER H. STEMER (Reg.No.34,956)  
RALPH E. LOCHER (Reg.No. 41,947)

Address all correspondence and telephone calls to:

LERNER AND GREENBERG, P.A.  
POST OFFICE BOX 2480  
HOLLYWOOD, FLORIDA 33022-2480  
TEL: (954) 925-1100  
FAX: (954) 925-1101

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

FULL NAME OF SOLE INVENTOR:

DIETER DRAXELMAYR

INVENTOR'S SIGNATURE: \_\_\_\_\_

DATE: \_\_\_\_\_

Residence: VILLACH, AUSTRIA

Country of Citizenship: AUSTRIA

Post Office Address: TSCHINOWITSCHERWEG 46  
A-9500 VILLACH  
AUSTRIA

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